ECE 111 - Homework #14

ECE 343 Signals & Systems

Filter Analysis

1) A filter has the following transfer function

$$Y = \left(\frac{400(s+1)}{(s+5)(s+7)(s+9)}\right) X$$

1a) What is the differential equation relating X and Y?

Multiply out and cross multiply. In Matlab

>> poly([-5, -7, -9])
ans = 1 21 143 315

$$Y = \left(\frac{400s + 400}{s^3 + 21s^2 + 143s + 315}\right)X$$
(s³ + 21s² + 143s + 315)Y = (400s + 400)X

Note that sY means *the derivative of y*

$$y''' + 21y'' + 143y' + 315y = 400x' + 400x$$

1b) Find y(t) assuming x(t) = 5

Use phasor analysis.

s = 0
X = 5

$$Y = \left(\frac{400(s+1)}{(s+5)(s+7)(s+9)}\right)_{s=0} \cdot (5)$$

Y = 6.3492
 $y(t) = 6.3492$

In Matlab

```
>> s = 0;

>> X = 5;

>> Y = 400*(s+1) / ( (s+5)*(s+7)*(s+9) ) * X

Y = 6.3492
```

1c) Find y(t) assuming $x(t) = 5 \sin(3t)$

s = j3
X = 0 - j5 real = cosine, -imag = sine

$$Y = \left(\frac{400(s+1)}{(s+5)(s+7)(s+9)}\right)_{s=j3} \cdot 0 - j5X$$

In Matlab

meaning

$$y(t) = -0.2705\cos(3t) + 15.0101\sin(3t)$$

On an HP Prime (in RPN mode)

400 enter 1i3 * 5i3 / 7i3 / 9i3 / 0i-5 *



2) Plot the gain vs. frequency for this filter from 0 to 30 rad/sec.

```
Y = (400(s+1)
(s+5)(s+7)(s+9))X
>> w = [0:0.01:30]';
>> s = j*w;
>> G = 400*(s+1) ./ ((s+5).*(s+7).*(s+9));
>> plot(w,abs(G))
>> xlabel('Frequency (rad/sec)');
>> ylabel('Gain');
>>
```



3) Plot the gain vs. frequency for this filter from 0 to 30 rad/sec.

$$Y = \left(\frac{10,000}{(s^2+18.5s+100)(s^2+7.6s+100)}\right)X$$
>> w = [0:0.01:30]';
>> s = j*w;
>> G = 10000 ./ ((s.^2 + 18.5*s + 100).*(s.^2 + 7.6*s + 100));
>> plot(w,abs(G))
>> xlabel('Frequency (rad/sec)');
>> ylabel('Gain');
>>



Filter Design

Problem 4-6) Design a filter of the following form so that the gain matches the graph below:



 $G(s) = \left(\frac{a}{\left(s^2 + bs + c\right)\left(s^2 + ds + e\right)\left(s^2 + fs + g\right)}\right)$

4) Write an m-file, cost.m, which

- Is passed an array, z, with each element representing (a, b, c, d, e, f, g)
- Computes the gain, G(s) for this value of (a, b, c, d, e, f, g)
- Computes the difference between the gain, G, and the target (above), and
- Returns the sum-squared error in the gain

```
function [J] = costf(z)
a = z(1);
b = z(2);
c = z(3);
d = z(4);
e = z(5);
f = z(6);
g = z(7);
w = [0:0.01:10]' + 1e-6;
s = j * w;
g1 = 1 * (w < 2);
g2 = (-0.2*w + 1.4).*(w>2).*(w<4);
g3 = 0.6 * (w>4).*(w<6);
g4 = (-0.3*w + 2.4) .* (w>6) .* (w<8);
Gideal = g1 + g2 + g3 + g4;
G = a ./ ((s.^2 + b*s + c) .* (s.^2 + d*s + e) .* (s.^2 + f*s + g));
G = abs(G);
E = abs(Gideal) - abs(G);
J = sum(E .^{2});
plot(w,Gideal,w,abs(G),'r');
ylim([0,1.4]);
pause(0.01);
end
```

5) Use your m-file to determine how 'good' the following filter is:

$$G(s) = \left(\frac{a}{(s^2 + bs + c)(s^2 + ds + e)(s^2 + fs + g)}\right) = \left(\frac{2304}{(s^2 + s + 4)(s^2 + s + 16)(s^2 + s + 36)}\right)$$

>> costF([2304,1,4,1,16,1,36])

ans = 682.0555



6) Use fminsearch() to find the 'best' filter of the form

$$G(s) = \left(\frac{a}{\left(s^2 + bs + c\right)\left(s^2 + ds + e\right)\left(s^2 + fs + g\right)}\right)$$

a) Give the resulting (a, b, c, d, e, f, g)

/

```
>> [Z,e] = fminsearch('costF', [2304,1,4,1,16,1,36])
```

```
Z =

a b c d e f

7.1473e+003 3.3233e+000 5.8652e+000 5.4393e+000 3.0569e+001 1.4878e+000

g

4.0737e+001

e = 0.6354
```

b) Give the resulting filter, and

$$G(s) = \left(\frac{7147.3}{\left(s^2 + 3.32s + 5.86\right)\left(s^2 + 5.43s + 30.56\right)\left(s^2 + 1.48s + 40.73\right)}\right)$$

c) Plot the 'optimal' filter's gain vs. frequency

