

ECE 111 - Homework #11

Week #11 - ECE 343 Signals- Due 8am Tuesday, April 5th
Please submit as a Word or pdf file and email to Jacob_Glower@yahoo.com with header ECE 111 HW#11

Problem 1-5) Let $x(t)$ be a function which is periodic in 2π

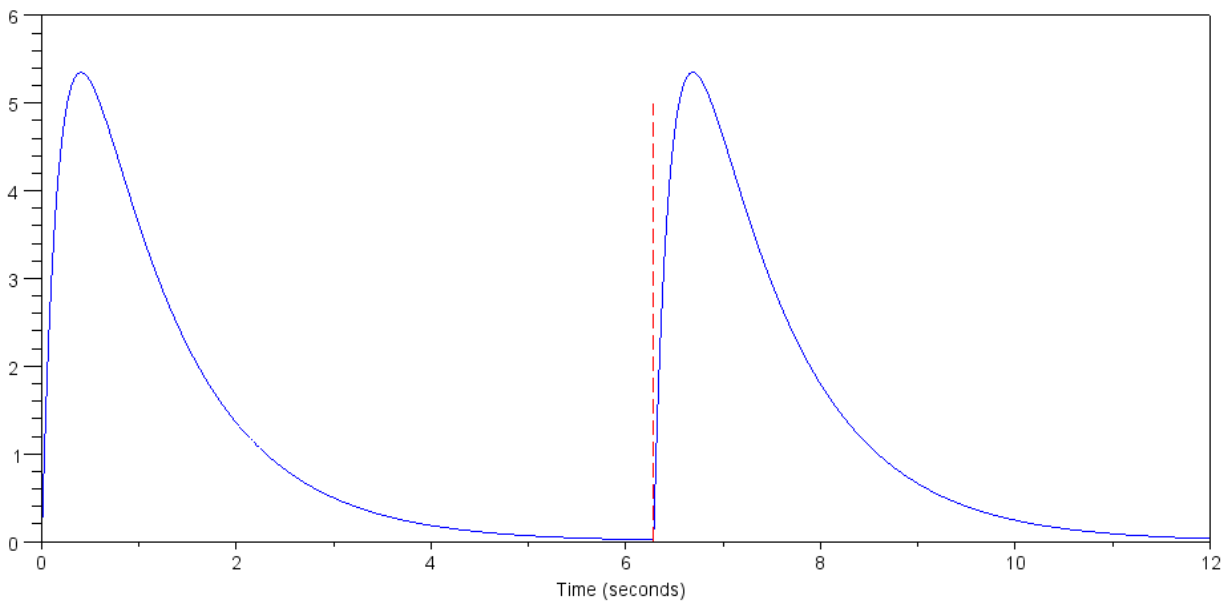
$$x(t) = x(t + 2\pi)$$

Over the interval $(0, 2\pi)$ $x(t)$ is

$$x(t) = 5e^{-t} - 5e^{-5t}$$

or in Matlab:

```
t = [0:0.001:2*pi]';  
x = 5 * exp(-t) - 5 * exp(-5*t);  
plot(t, x)
```



$x(t)$ Note that $x(t)$ repeats repeats every 2π seconds

Curve Fitting with a power series:

1) Using least squares, approximate $x(t)$ over the interval $(0, 2\pi)$ as

$$x(t) \approx a + bt + ct^2 + dt^3$$

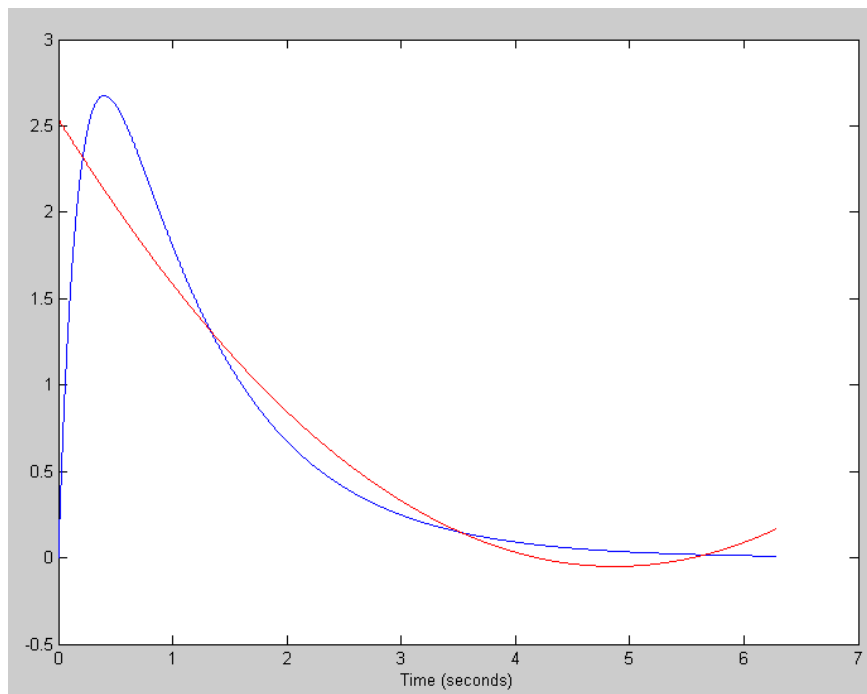
Plot $x(t)$ along with it's approximation.

```
>> t = [0:0.001:2*pi]';  
x = 5 * exp(-t) - 5 * exp(-5*t);  
plot(t,x)  
>>  
>> B = [t.^3, t.^2, t, t.^0];  
>> A = inv(B'*B)*B'*x
```

A =

```
-0.0001  
0.1096  
-1.0639  
2.5387
```

```
>> plot(t,x,'b',t,B*A,'r')  
>> xlabel('Time (seconds)');  
>>
```



Curve Fitting using a Fourier Series

2) Using least squares, approximate $x(t)$ over the interval $(0, 2\pi)$ as

$$x(t) = a_0 + a_1 \cos(t) + b_1 \sin(t) + a_2 \cos(2t) + b_2 \sin(2t) + a_3 \cos(3t) + b_3 \sin(3t)$$

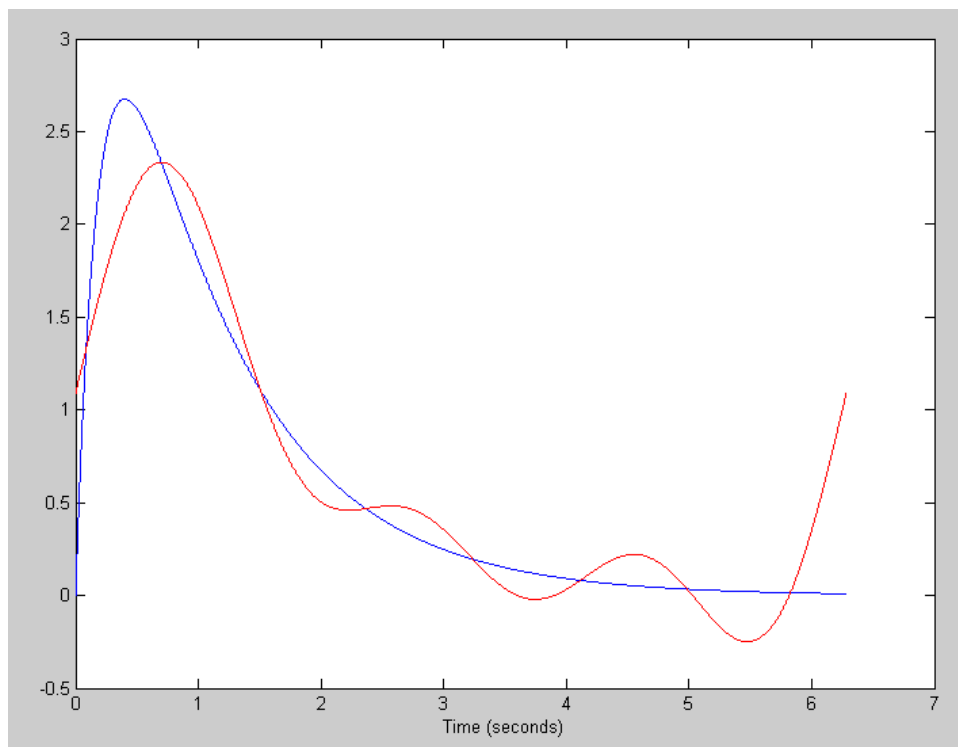
Plot $x(t)$ along with it's approximation.

```
>> B = [t.^0, cos(t), sin(t), cos(2*t), sin(2*t), cos(3*t), sin(3*t)];  
>> A = inv(B'*B)*B'*x
```

A =

```
0.6350  
0.4879  
0.7331  
0.0430  
0.5257  
-0.0755  
0.3361
```

```
>> plot(t,x,'b',t,B*A,'r')  
>> xlabel('Time (seconds)');  
>>
```



Superposition

3) Assume X and Y are related by

$$Y = \left(\frac{2}{s^2 + 2s + 2} \right) X$$

3a) Determine x(t) in terms of its Fourier Transform out to 3 rad/sec

```
>> a0 = mean(x)
a0 =    0.6351
>> a1 = 2*mean(x .* cos(t))
a1 =    0.4882
>> b1 = 2*mean(x .* sin(t))
b1 =    0.7330
>> a2 = 2*mean(x .* cos(2*t))
a2 =    0.0433
>> b2 = 2*mean(x .* sin(2*t))
b2 =    0.5256
>> a3 = 2*mean(x .* cos(3*t))
a3 =   -0.0752
>> b3 = 2*mean(x .* sin(3*t))
b3 =    0.3361
```

Note that this is the same result we got for problem #2

```
>> A = inv(B'*B)*B'*x
    0.6350
    0.4879
    0.7331
    0.0430
    0.5257
   -0.0755
    0.3361
```

Fourier Transforms is just least-squares curve fitting with a basis of sine and cosine functions.

3b) Plot x(t) and its Fourier approximation taken out to 3 rad/sec
same answer as problem #2

4) Determine the gain of this filter at each frequency present in problem #2 (i.e. 0, 1, 2, 3 rad/sec)

- *note: You should get a complex number for the gain at each frequency*

```
>> s = 0;  
>> G0 = 2 / (s^2 + 2*s + 2)
```

```
G0 = 1
```

```
>> s = j*1;  
>> G1 = 2 / (s^2 + 2*s + 2)
```

```
G1 = 0.4000 - 0.8000i
```

```
>> s = j*2;  
>> G2 = 2 / (s^2 + 2*s + 2)
```

```
G2 = -0.2000 - 0.4000i
```

```
>> s = j*3;  
>> G3 = 2 / (s^2 + 2*s + 2)
```

```
G3 = -0.1647 - 0.1412i
```

5a) Determine the phasor representation for $Y(j\omega)$ at each frequency.

- *note: You should get a complex number for Y - the phasor representation for $y(t)$ at 0, 1, 2, and 3 rad/sec*

Output = Gain * Input

$Y = G * X$

```
>> % DC
>> s = 0;
>> y0 = 2 / (s^2 + 2*s + 2) * a0

y0 =    0.6351

>> % 1 rad/sec
>> s = j*1;
>> y1 = 2 / (s^2 + 2*s + 2) * ( a1 - j*b1 )

y1 =  -0.3911 - 0.6837i

>> % 2 rad/sec
>> s = j*2;
>> y2 = 2 / (s^2 + 2*s + 2) * ( a2 - j*b2 )

y2 =  -0.2189 + 0.0878i

>> % 3 rad/sec
>> s = j*3;
>> y3 = 2 / (s^2 + 2*s + 2) * ( a3 - j*b3 )

y3 =  -0.0351 + 0.0660i
```

5b) From this, determine $y(t)$

- real = cosine, -imag = sine

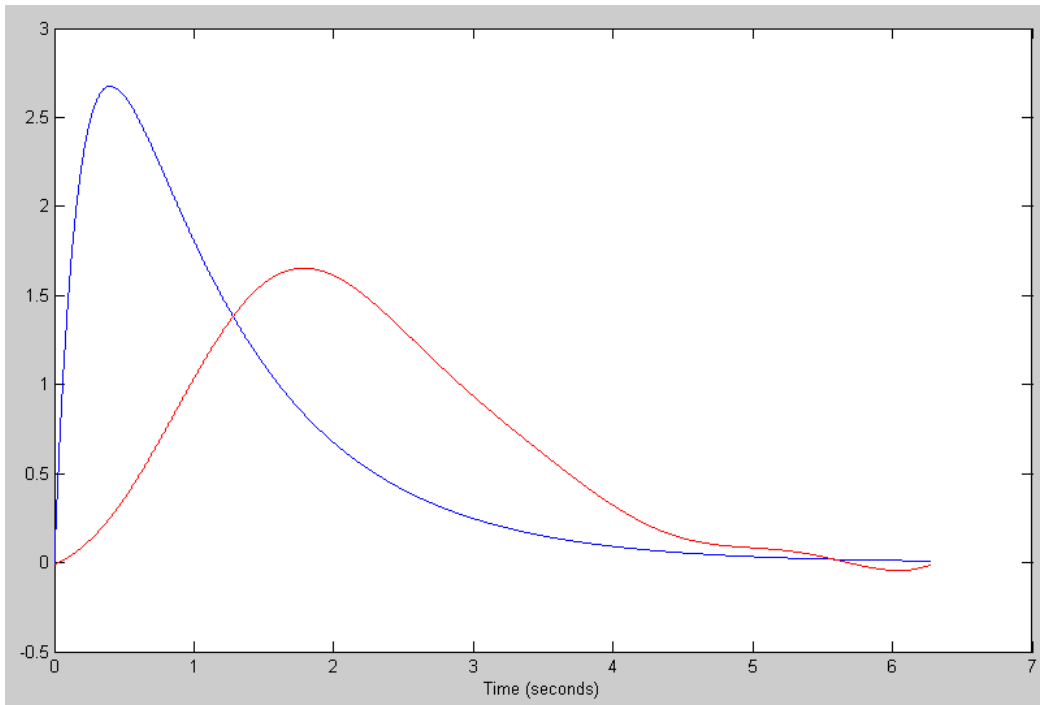
$$y(t) = 0.6351 - 0.3911 \cos(t) + 0.6831 \sin(t) - 0.2189 \cos(2t) - 0.0878 \sin(2t) - 0.0351 \cos(3t) - 0.0660 \sin(3t)$$

Note:

- In theory, you need an infinite number of terms
- In practice, the terms go to zero fairly quickly. Truncating after the 3rd harmonic gives a close approximation to $y(t)$

6) Plot $x(t)$ and $y(t)$.

```
>> y = y0 + real(y1)*cos(t) - imag(y1)*sin(t);  
>> y = y + real(y2)*cos(2*t) - imag(y2)*sin(2*t);  
>> y = y + real(y3)*cos(3*t) - imag(y3)*sin(3*t);  
>> plot(t,x,'b',t,y,'r')  
>> xlabel('Time (seconds)');  
>>
```



$x(t)$ (blue) and $y(t)$ (red)