

ECE 111 - Homework #10

ECE 343 Signals & Systems- Due Due 8am, Tuesday, March 29th
Please submit as a Word or pdf file and email to Jacob_Glower@yahoo.com with header ECE 111 HW#10

1) A filter has the following transfer function

$$Y = \left(\frac{6s+30}{s^2+6s+60} \right) X$$

1a) What is the differential equation relating X and Y?

$$(s^2 + 6s + 60)Y = (6s + 30)X$$

$$y'' + 6y' + 60y = 6x' + 30x$$

or

$$\frac{d^2y}{dt^2} + 6\frac{dy}{dt} + 60y = 6\frac{dx}{dt} + 30x$$

1b) Find y(t) assuming $x(t) = 5$

At DC (0 rad/sec)

$$X = 5$$

$$Y = \left(\frac{6s+30}{s^2+6s+60} \right)_{s=0} \cdot (5)$$

$$Y = 2.5$$

1c) Find y(t) assuming $x(t) = 5 \cos(7t)$

At 7 rad/sec

$$X = 5 + j0 \quad \text{real} = \text{cosine, -imag} = \text{sine}$$

$$Y = \left(\frac{6s+30}{s^2+6s+60} \right)_{s=j7} \cdot (5 + j0)$$

$$Y = 5.5544 - j2.1167$$

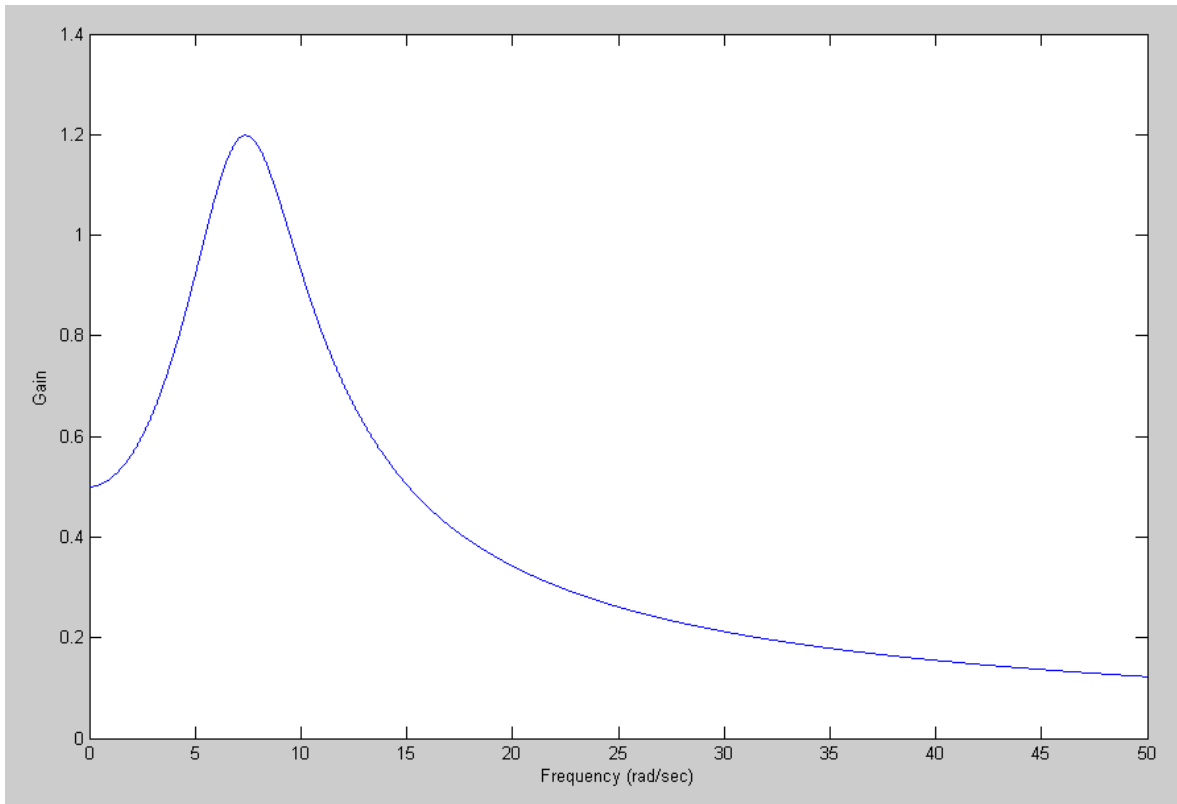
meaning

$$y(t) = 5.5544 \cos(7t) + 2.1167 \sin(7t)$$

2) Plot the gain vs. frequency for this filter from 0 to 50 rad/sec.

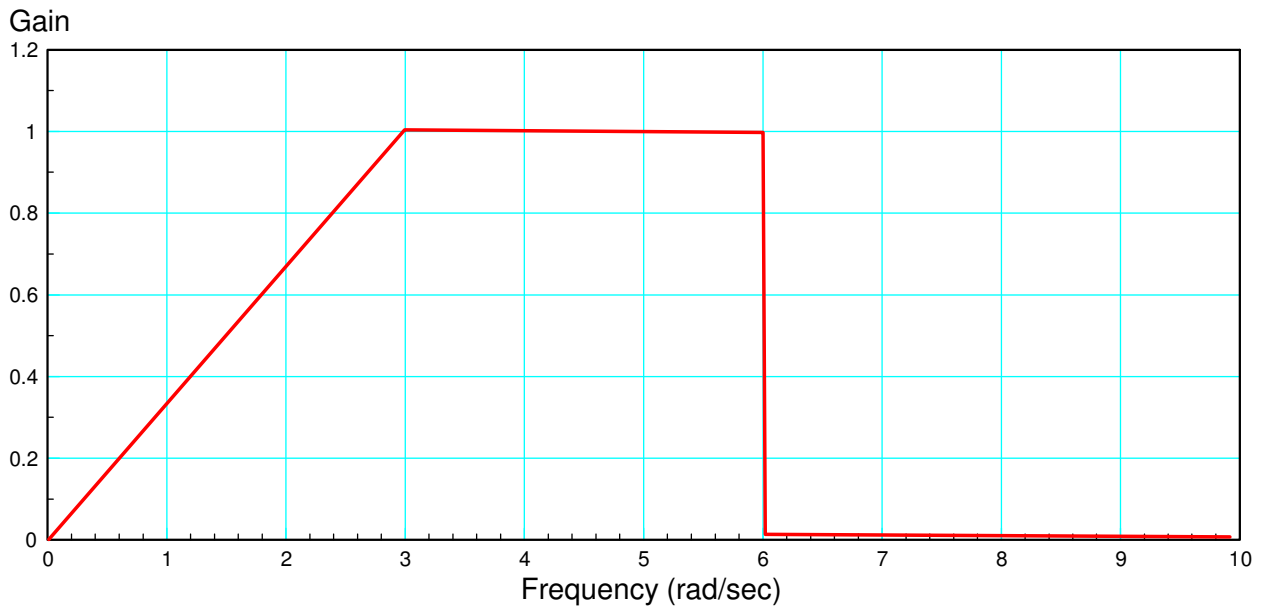
$$Y = \left(\frac{6s+30}{s^2+6s+60} \right) X$$

```
>> w = [0:0.01:50]';  
>> s = j*w;  
>> G = (6*s+30) ./ (s.^2 + 6*s + 60);  
>> plot(w,abs(G))  
>> xlabel('Frequency (rad/sec)');  
>> ylabel('Gain');  
>>
```



Problem 3-5) Design a filter of the following form so that the gain matches the graph below:

$$G(s) = \left(\frac{as}{(s^2+bs+c)(s^2+ds+e)(s^2+fs+g)} \right)$$



3) Write an m-file, cost.m, which

- Is passed an array, z, with each element representing (a, b, c, d, e, f, g)
- Computes the gain, G(s) for this value of (a, b, c, d, e, f, g)
- Computes the difference between the gain, G, and the target (above), and
- Returns the sum-squared error in the gain

```
function [ J ] = Filter( z )

z = abs(z);
a = z(1);
b = z(2);
c = z(3);
d = z(4);
e = z(5);
f = z(6);
g = z(7);

w = [0:0.01:10]';
s = j*w;

Gideal = (w/3).* (w<3) + (0*w + 1) .* (w>=3) .* (w<6);

G = a*s ./ ( (s.^2 + b*s + c) .* (s.^2 + d*s + e) .* (s.^2 + f*s + g) );
G = abs(G);
E = abs(Gideal) - abs(G);

J = sum(E .^ 2);

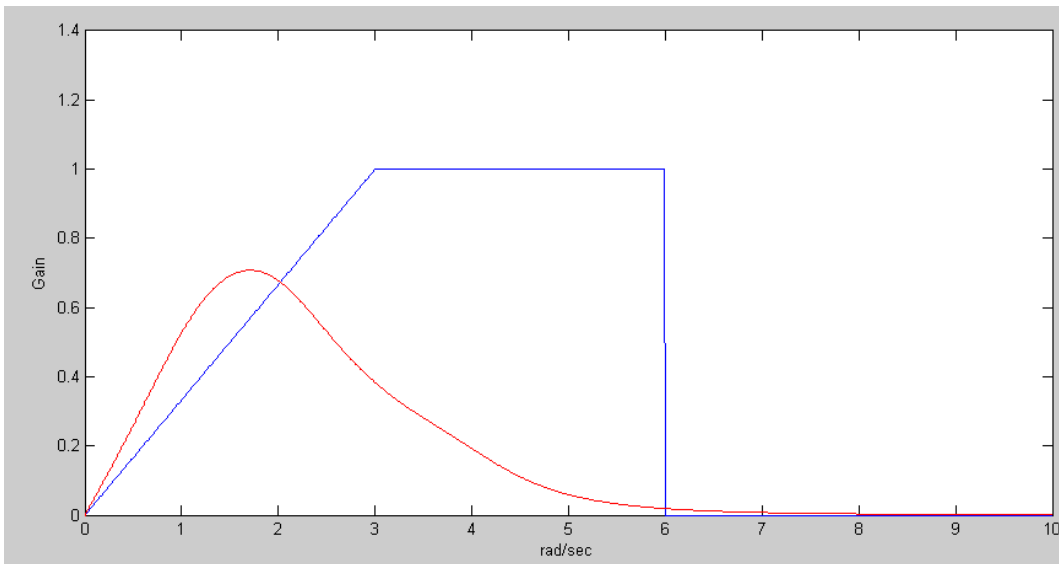
plot(w,Gideal,w,abs(G),'r');
xlabel('rad/sec');
ylabel('Gain');
ylim([0,1.4]);
pause(0.01);
end
```

4) Use your m-file to determine how 'good' the following filter is:

$$G(s) = \left(\frac{as}{(s^2+bs+c)(s^2+ds+e)(s^2+fs+g)} \right) = \left(\frac{85s}{(s^2+2s+2)(s^2+2s+5)(s^2+2s+17)} \right)$$

```
>> Filter([85,2,2,2,5,2,17])
```

```
ans = 239.4441
```



5) Use `fminsearch()` to find the 'best' filter of the form

$$G(s) = \left(\frac{as}{(s^2+bs+c)(s^2+ds+e)(s^2+fs+g)} \right)$$

5a) Give the resulting (a, b, c, d, e, f, g)

```
>> [Z,e] = fminsearch('Filter',Z)
```

```
Z =      a      b      c      d      e      f      g
     431.6913   1.9651   3.9000   0.7258  31.0840   1.8625  14.8573
```

```
e =
```

```
11.4704
```

5b) Give the resulting filter, and

$$G(s) = \left(\frac{431.69s}{(s^2+1.96s+3.9)(s^2+0.72s+31.08)(s^2+1.86s+14.85)} \right)$$

5c) Plot the 'optimal' filter's gain vs. frequency

