## ECE 111 - Homework #14

ECE 343 Signals & Systems Due Monday, November 27th

## **Filter Analysis**

1) A filter has the following transfer function

$$Y = \left(\frac{10(s+2)}{(s+0.5)(s+6)(s+7)}\right) X$$

1a) What is the differential equation relating X and Y?

Cross multiply and multiply out

$$((s+0.5)(s+6)(s+7))Y = 10(s+2)X$$
$$(s^{3}+13.5s^{2}+48.5s+21)Y = (10s+20)X$$

Note that sY means *the derivative of* y(t)

$$y''' + 13.5y'' + 48.5y' + 21y = 10x' + 20x$$

## 1b) Find y(t) assuming x(t) = 5

At DC, s = 0

$$Y = \left(\frac{10(s+2)}{(s+0.5)(s+6)(s+7)}\right)_{s=0} \cdot (5)$$
$$Y = 4.762$$

1c) Find y(t) assuming  $x(t) = 5 \sin(2t)$ 

$$s = j2$$

$$X = 0 - j5$$

$$Y = \left(\frac{10(s+2)}{(s+0.5)(s+6)(s+7)}\right)_{s=j2} \cdot (0 - j5)$$
>> s = j\*2;  
>> X = 0 - j\*5;  
>> Y = 10\*(s+2) / ((s+0.5)\*(s+6)\*(s+7)) \* X  
Y = -1.3541 - 0.6215i

meaning

$$y(t) = -1.3541\cos(2t) + 0.6215\sin(2t)$$

2) Plot the gain vs. frequency for this filter from 0 to 50 rad/sec.

```
    Low-Pass Filter
```

```
Y = \left(\frac{50,000}{(s+4.8)(s^2+11.3s+51.8)(s^2+4.69s+123)}\right)X
>> w = [0:0.01:50]';
>> s = j*w;
>> G2 = 50e3 ./ ( (s+4.8).*(s.^2 + 11.3*s + 51.8).*(s.^2 + 4.69*s + 123) );
>> plot(w,abs(G2))
>> xlabel('frequency (rad/sec)');
>> ylabel('Gain');
```



3) Plot the gain vs. frequency for this filter from 0 to 50 rad/sec.

$$Y = \left(\frac{200 \cdot s^2}{(s+1\pm j5)(s+1\pm j15)}\right) X = \left(\frac{200 \cdot s^2}{(s^2+2s+26)(s^2+2s+226)}\right) X$$

$$>> w = [0:0.01:50]';$$

$$>> s = j*w;$$

$$>> G = 200*s.^2 ./ ((s+1+j*5).*(s+1-j*5).*(s+1+j*15).*(s+1-j*15));$$

$$>> plot(w, abs(G))$$

$$>> xlabel('frequency (rad/sec)');$$

$$>> ylabel('Gain');$$



## **Filter Design**

4) Write an m-file, cost.m, which

- Is passed an array, z, with each element representing (a, b, c, d, e, f, g)
- Computes the gain, G(s) for this value of (a, b, c, d, e, f, g)
- Computes the difference between the gain, G, and the target (above), and
- Returns the sum-squared error in the gain



Step 1: Come up with a model for G(s). Use piecewise linear funcitons

| G = 0.8               | w < 2     |
|-----------------------|-----------|
| $G = 0.2\omega + 0.4$ | 2 < w < 4 |
| $G = 2 - 0.2\omega$   | 4 < w < 6 |
| G = 5.6 - 0.8w        | 6 < w < 7 |
| G = 0                 | w > 7     |

```
Code:
```

```
function [J] = costF(z)
   a = z(1);
   b = z(2);
   c = z(3);
   d = z(4);
   e = z(5);
   f = z(6);
   g = z(7);
   w = [0:0.1:10] ' + 1e-6;
   s = j * w;
   G1 = 0.8 * (w < 2);
   G2 = (0.2*w+0.4) \cdot (w>2) \cdot (w<4);
   G3 = (2 - 0.2*w) \cdot (w>4) \cdot (w<6);
   G4 = (5.6 - 0.8*w) \cdot (w>6) \cdot (w<7);
   Gideal = G1 + G2 + G3 + G4;
   G = a ./ ((s.^2 + b*s + c).*(s.^2 + d*s + e).*(s.^2+f*s+g));
   e = abs(Gideal) - abs(G);
   J = sum(e .^{2});
   plot(w,abs(Gideal),'r',w,abs(G),'b');
   ylim([0,1.2]);
   pause(0.01);
```

end

5) Use your m-file to determine how 'good' the following filter is:

$$G(s) = \left(\frac{a}{(s^2 + bs + c)(s^2 + ds + e)(s^2 + fs + g)}\right) = \left(\frac{2304}{(s^2 + s + 4)(s^2 + s + 16)(s^2 + s + 36)}\right)$$

```
>> costF([2304,1,4,1,16,1,36])
```

ans = 288.4235



6) Use fminsearch() to find the 'best' filter of the form

$$G(s) = \left(\frac{a}{\left(s^2 + bs + c\right)\left(s^2 + ds + e\right)\left(s^2 + fs + g\right)}\right)$$

a) Give the resulting (a, b, c, d, e, f, g)

b) Give the resulting filter, and

$$G(s) = \left(\frac{4004}{\left(s^2 + 4.72s + 7.89\right)\left(s^2 + 1.93s + 18.02\right)\left(s^2 + 1.00s + 35.89\right)}\right)$$

c) Plot the 'optimal' filter's gain vs. frequency



Note: You can design some pretty good filters using Matlab and fminsearch, even if you know nothing about filter design.